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**SEG T3 Driver for DeltaV  
Programmable Serial Interface Card  
Series 2**

**USER MANUAL**

**Rev. P1.10**

**October 12, 2003**

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# 1 INTRODUCTION

## 1.1 Scope

This document is the User Manual for the SEG T3 Scale serial communication driver firmware for the Emerson DeltaV Control System; it provides information required to install, configure, and maintain the SEG T3 driver firmware on the DeltaV Series 2 Programmable Serial Interface Card (PSIC). The reader should be familiar with Emerson’s DeltaV controller system and the SEG T3 Equipment. Specific SEG Weigh Scale supported is the T3.

The section *Document Format* briefly describes the contents of each section of this manual. *System Specifications* outlines hardware and software requirements for the SEG T3 Driver (P1.10) firmware. *Related Documents* lists other documents used to prepare this manual.

## 1.2 Document Format

This document is organized as follows:

<b>Introduction</b>	Describes the scope and purpose of this document.
<b>Theory of Operation</b>	Provides a general functional overview of the SEG T3 Weigh Scale Driver.
<b>Downloading Firmware</b>	Describes downloading procedures for the SEG T3 Driver firmware on to the DeltaV PSIC.
<b>PSIC Configuration</b>	Describes procedures and guidelines for configuring the DeltaV PSIC.
<b>Driver Communications</b>	Describes SEG T3 commands used and DeltaV Registers containing Weight data.
<b>Operational Check</b>	Provides tips and assistance to ensure PSIC is properly setup and configured.
<b>DeltaV - SEG T3 Electrical Interface</b>	Describes the electrical interface between DeltaV and the SEG T3 Weigh Scale. Also describes the pin assignments for RS-232 communications.
<b>Technical Support</b>	Describes who to call if you need assistance.



### 1.3 System Specifications

The following table lists the minimum hardware requirements for the SEG T3 Weigh Scale Driver:

**Table 1: System Specifications**

<b>Firmware</b>	SEG T3 Driver Firmware (P1.10)
<b>Protocol Compatibility</b>	SEG T3 Protocol as defined in the documents listed below: 1. S42-CSE Communications Specification.
<b>Software Requirements</b>	DeltaV System Software (Release 6.3 or later) installed on a hardware-appropriate Windows NT workstation configured as a ProPlus for DeltaV Serial Interface Port License (VE4102)
<b>Minimum Hardware Requirements</b>	FRSI DeltaV Serial Interface Series 2, Hardware PN: 12P2506X022 FRSI DeltaV M3, M5, MD or Series 2 MD Controller, Power Supply and 2 wide controller carrier FRSI 8 wide I/O card carrier SEG T3 devices



## **2 THEORY OF OPERATION**

As part of the serial interface port license, a standard Modbus protocol is installed on the DeltaV PSIC prior to customization. The PSIC needs to be flash upgraded from the Modbus protocol to the SEG T3 protocol before operation.

The RS-232 communication settings must be configured properly to ensure accurate communication between the PSIC and SEG T3 devices. RS-422/485 may be used if the SEG T3 devices support this electrical standard.

This driver functions as a master only. In master mode, the PSIC continuously sends weight and status read commands to the connected scale devices. The received responses are reported to DeltaV via dataset registers. When a user command is detected (commands are listed below), that command is sent out to the scale. The corresponding response Ack or Nak is reported back to the dataset.

In general, the primary functions of the driver are listed below:

Get Status Information  
Get Gross Weight  
Select Recipe  
Select Amount  
Clear Alarm  
Tare  
Pause Batch  
Cancel Batch  
Resume Batch  
Park Batch  
Comp. Start Batch  
Main Start Batch  
Start OK Batch  
Start Empty Batch  
Restart scale computer

- Performs data and message handling between DeltaV and SEG T3 devices.
- Checks validity of messages received from the SEG T3 devices.
- Processes reply information and updates the corresponding dataset registers
- Update dataset register status and data block status to indicate the communication state.

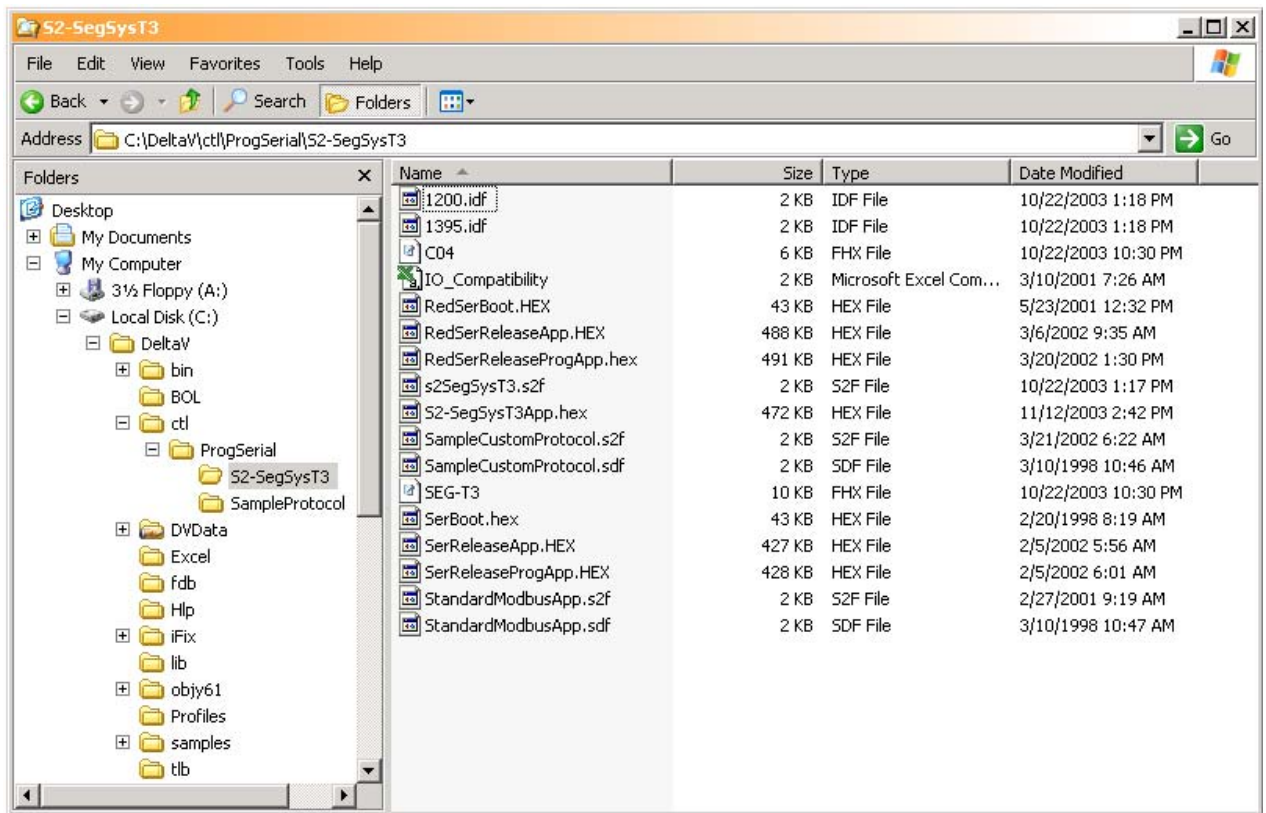


### 3 Downloading the firmware

The driver software comprises 17 files, distributed on a CD. These files must be copied to the DeltaV directory (you must create the directory first) on your ProPlus Workstation. The path is:

**\\DeltaV\ctl\ProgSerial\S2-SegSysT3**

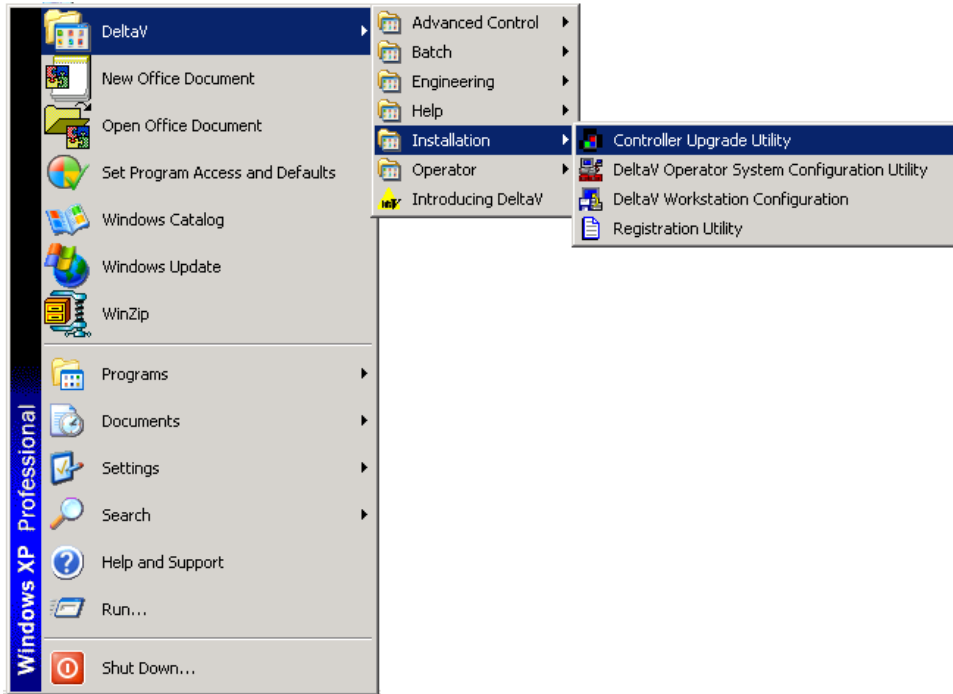
The following shows a completed copy operation:



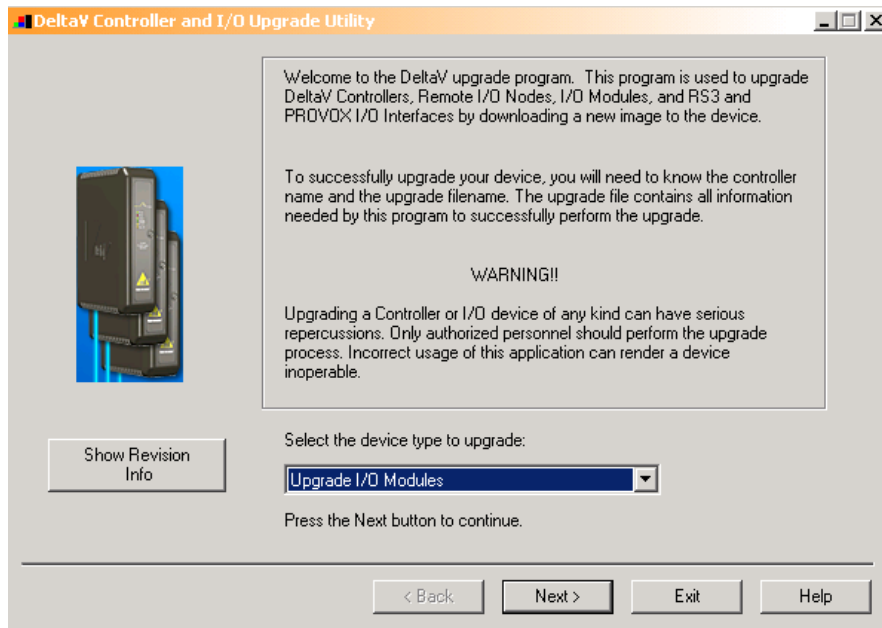
After copy completion, you are ready to program (or upgrade) the Programmable Serial Card with the supplied custom driver software. The steps are as follows:



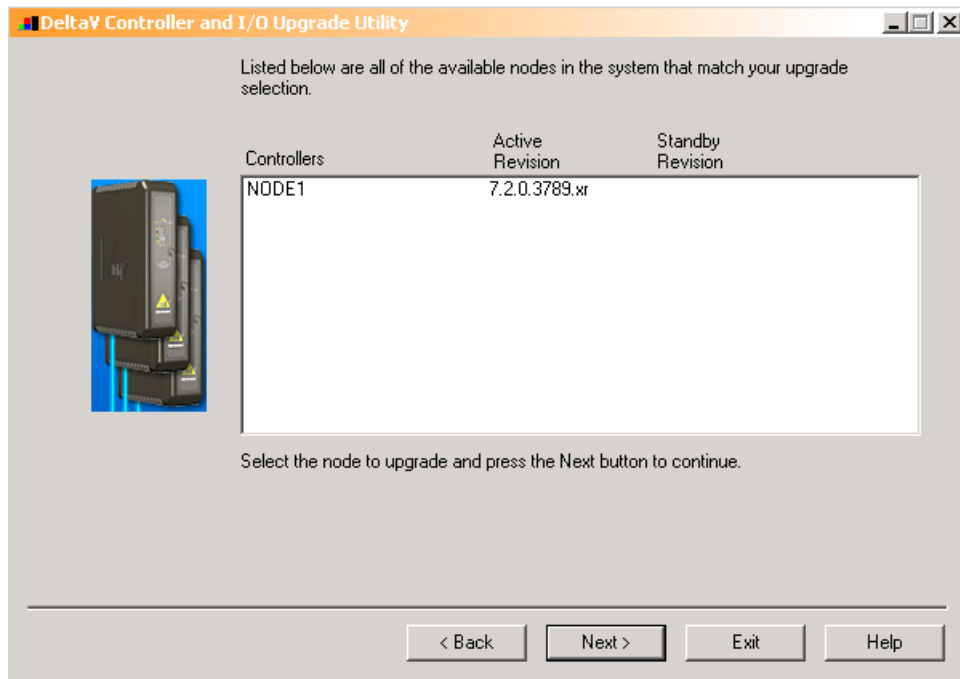
1. Click on the Start button and select DeltaV, Installation, Controller Upgrade Utility as shown below.



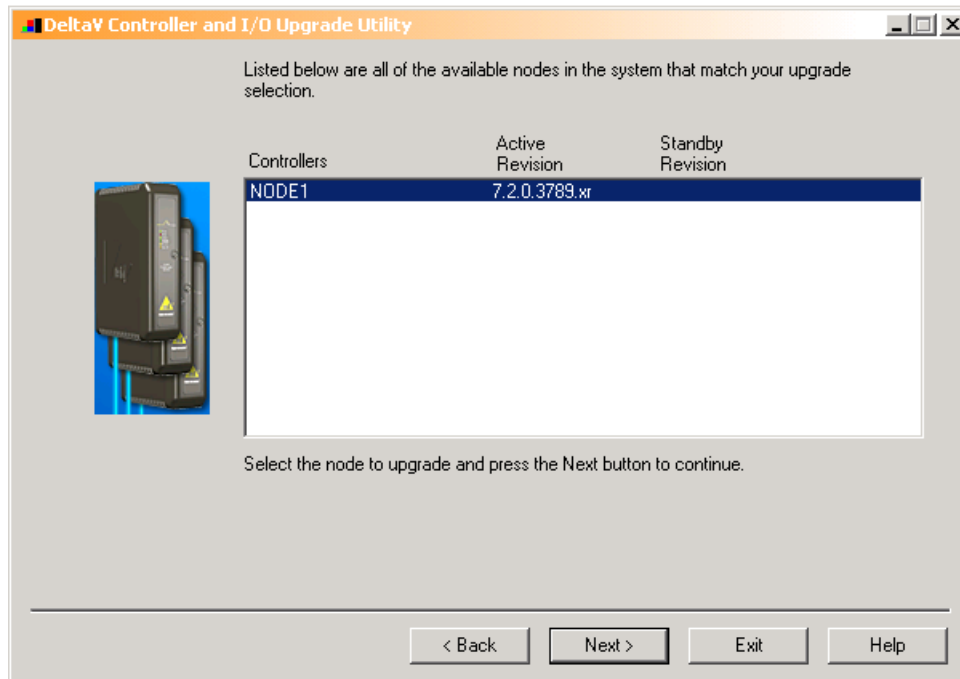
The following dialog will appear:



Choose Upgrade I/O Modules from the drop down menu as shown and click Next.

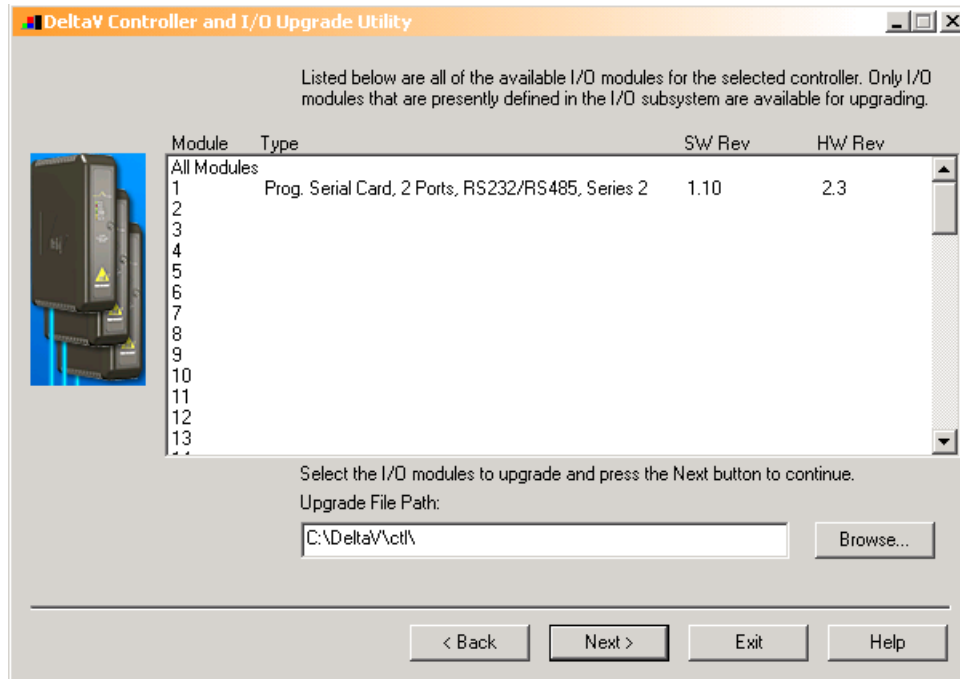


The above dialog will appear, listing all the available Controllers in your network. From this dialog, select the appropriate Controller and then Click Next as shown below.





After you Click Next, the following dialog will appear, listing all the I/O modules in your selected Controller. The shown list of I/O modules is an example only. Your list will be different.

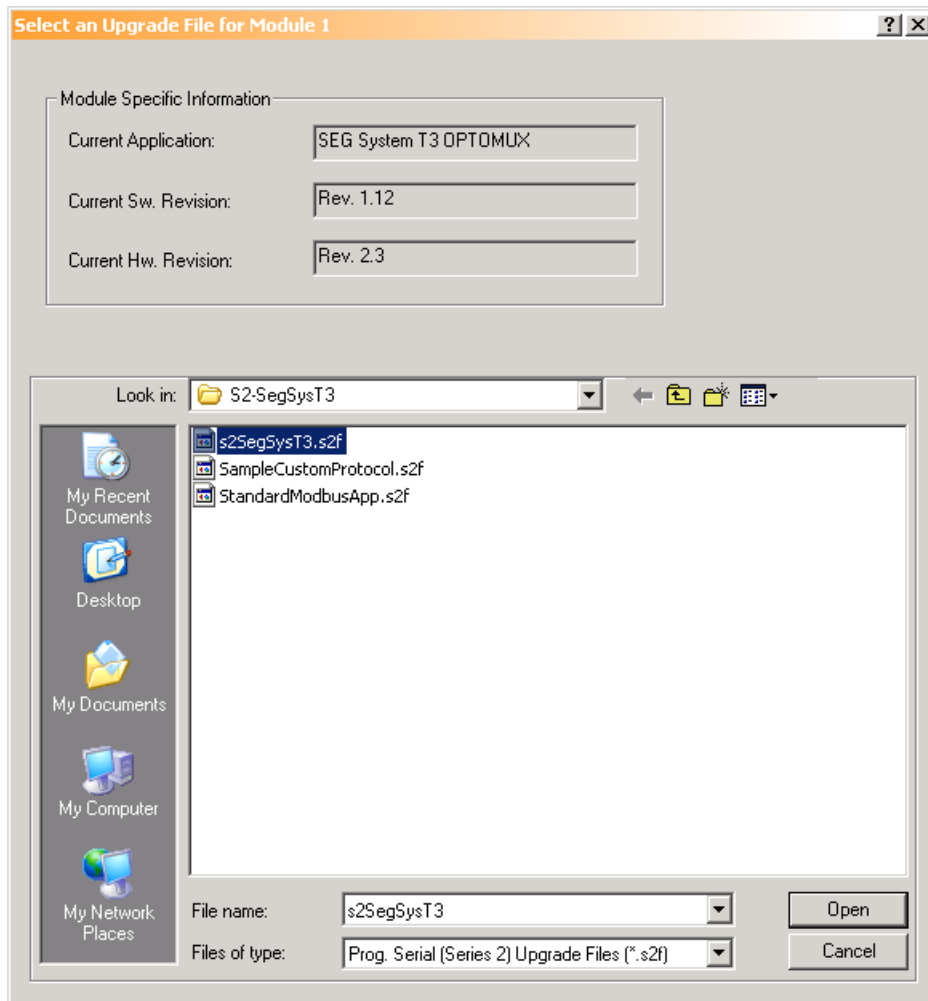


From this dialog, select the Programmable Serial Card I/O Module in the list. For example, we will select I/O Module 2. This will give you the following dialog, from which you will select the file path to where the driver software is located. This will be:

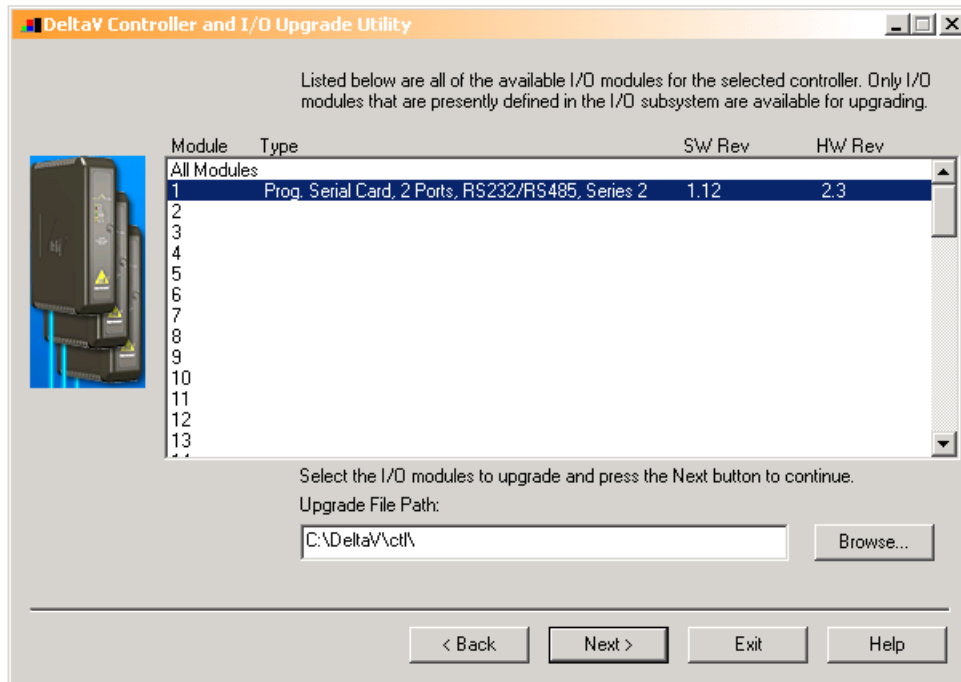
**\\DeltaV\ctl\ProgSerial\S2-SegSysT3**

Once you are in the specified directory, you will need to select the following file:

**S2SEGSYST3.S2F**

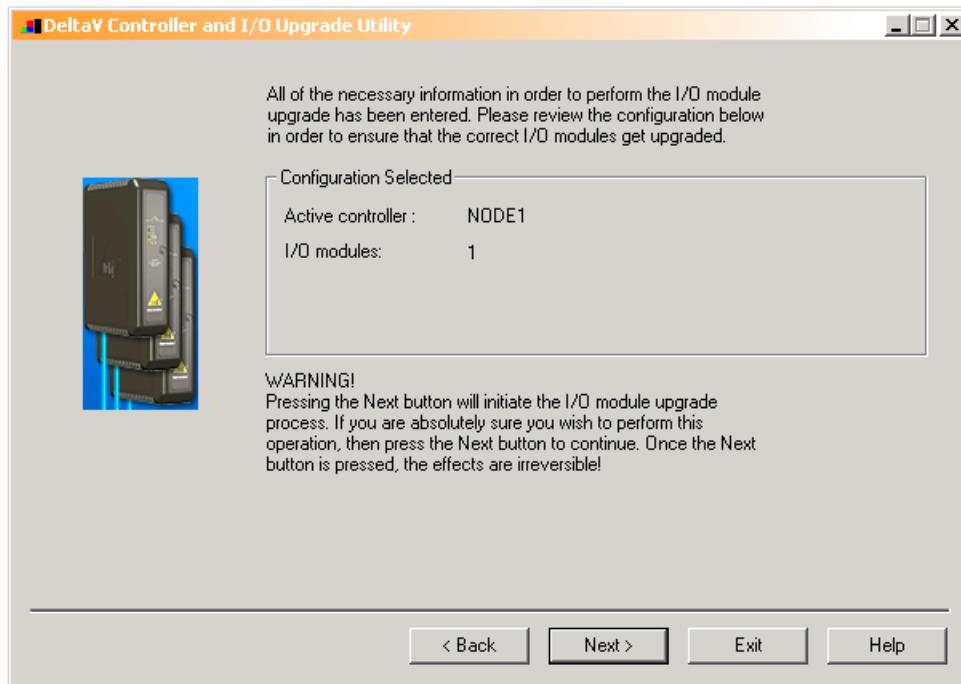


After selecting the .S2F file, Click on Open. This dialog will close and you will be back to the following:

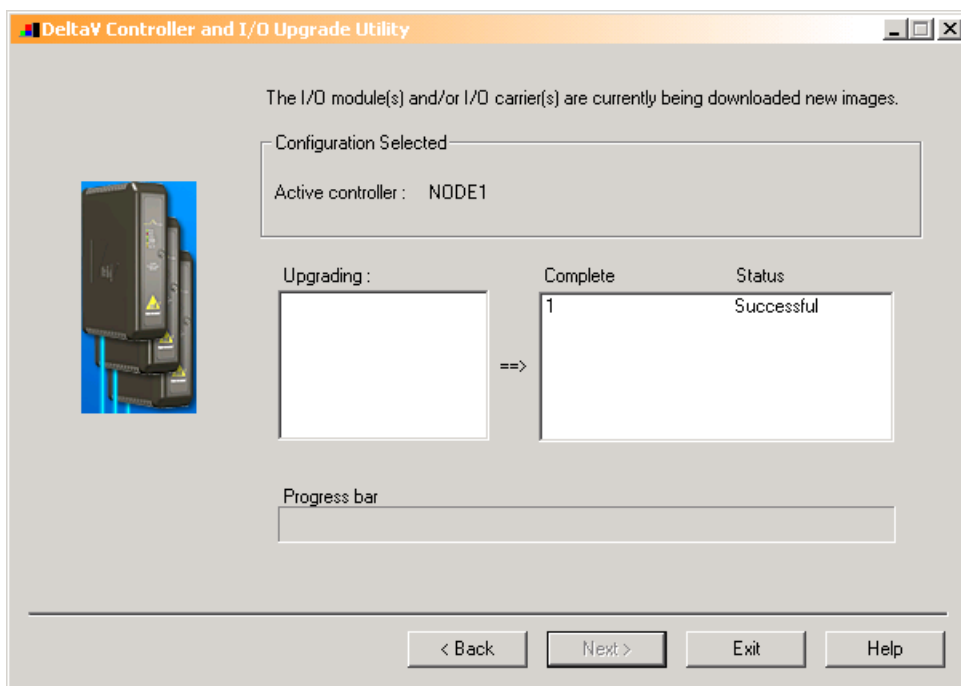


In this dialog, Click Next again.

You will get the following dialog, confirming the Controller and I/O Module to program.



Click Next and the I/O Module upgrade process will begin. After completion, you will receive the following dialog, indicating success.



This completes the I/O Module upgrade process.



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## 4 CONFIGURATION INFORMATION

This section describes the steps necessary to configure the DeltaV PSIC and the SEG T3 Weigh Scale to obtain proper communication.

### 4.1 Device And Dataset Configuration

The following paragraphs discuss some attributes in the device and dataset configuration:

#### 4.1.1 Device Address:

You can configure a maximum of 1 device, representing a weigh scale connected to a PSIC port. The device address is not used in communications.

#### 4.1.2 Output Mode:

Two output modes are available in the DeltaV PSIC: block output (0) and single output (1). This value is a don't care for the driver. Leave this value at its default setting of 0.

#### 4.1.3 DeltaV Data Type:

DeltaV data type can be configured as Floating point with status, or string, depending on the type of data requested. This is described below.

#### 4.1.4 DeviceDataType

The Device Data Type value determines the communication command used. The following Data Types are supported:

Table 1 – Device Types

Device Data Type	DeltaV Data Type	Description
1	Floating Point	Data values (Read/Write) SICS Read commands: S, SI, SX, SXI SICS Write commands: @, Z, T, TI, TA, TAC, R0, R1, U
2	String	SICS I2 command -Weighing Terminal and Weighing Platform data (Read only)
3	String	SICS I3 command – Software version (Read only)
4	String	SICS I4 command – Serial number (Read only)
5	String or UINT8	SICS AR command – Application Block Read only
6	Floating Point	SICS AW command – Application Block Write only



4.1.5 Data Start Address and Number of Values

Configure the Start Address as the default value of 9. The Number of values in each dataset will vary as described below:

Table 2 – Number of Values

Device Data Type	Number of Values	Description
1	21	Maximum 21 values
2	100	String Length
3	100	String Length
4	100	String Length
5	100	String Length or number of 8-bit registers
6	50	Maximum 50 values. This is based on Application Block size.

4.1.6 Special Data 1-5

Under the Special data tab, only the Special data 1 and Special data 2 fields are used as follows:

Table 3 – Special Data Values

Special Data	Value	Usage
1	n	a. This value is used to determine which SICS read command to use. Use 1-S command, 2-SI command, 3-SX command, and 4-SXI command. All other values are ignored. b. This value is 1-999 if Device Data Type is AR/AW. This number is the application block number.
2	1-100	Application sub-block number if Device Data Type is AR/AW.
3-5		Not Used



**4.2 Serial Driver Communications**

Two PSIC datasets will be allocated for each connected SEG T3. The PSIC can communicate with SEG T3 devices using RS-232 or RS-485. More than one device can be connected to a single PSIC port. Each device will use 2 datasets; consequently, a maximum of 8 devices will be supported on a single port.

The first dataset will be configured as Floating Point with Status. Only three registers of this dataset will be used as follows.

<b>Register</b>	<b>Dataset 1 – Floating Point with Status</b>	<b>Description</b>
1	Scale data	Data format XXXXX.X This data is read from the scale
2	DOSGEW_CALC	Data format XXXXX.X This data is sent to the scale
3	PARAM	Data format XXXXX.X This data is sent to the scale

The second dataset will be configured as 16-bit integer with status. Only 6 registers of this dataset will be used. These are described below:

<b>Register</b>	<b>Dataset 2 – 16-bit Integer with Status</b>	<b>Description</b>
1	In Command	=1 Get Status Information =2 Get Gross Weight =3 Select Recipe =4 Select Amount =5 Clear Alarm =6 Tare =7 Pause Batch =8 Cancel Batch =9 Resume Batch =10 Park Batch =11 Comp. Start Batch =12 Main Start Batch =13 Start OK Batch =14 Start Empty Batch =15 Restart scale computer
2	New Command	=0 No New Command =1 New Command to Execute
3	Command Executed	=1 Command Executed =0 Command in progress
4	Batch State	Read from weight computer
5	Result	Result of communication message
6	Error Code	Error code



4.2.1 Reading from SEG T3

The driver will send user selected commands to the SEG T3. The scale will respond with the current weight data, or other message specific data. This data will be parsed and written to dataset registers.

4.2.2 Writing to SEG T3

For writing to SEG T3, the driver will perform the following steps:

1. Wait for dataset 2, register 2 to be set to 1.
2. Set dataset 2, register 3 to 0 indicating command in progress.
3. Read the command number from dataset 2, register 1, format the command message and send it to the Sartorius. Some commands require user specified data. This will be read from dataset 1, registers 2 and/or 3.
4. Wait for SEG T3 to respond.
5. Update registers with new data and/or error code.
6. Set dataset 2, register 3 to 1 indicating command done.
- 7.

The driver will continuously send commands to read the weight and status from the Weigh Scales. If there are communication errors, these are reported up to DeltaV. Each weigh scale will always have only the following registers configured:

Table 5 - Supported Commands

Command Number	Parameters Required	Description
1	0	SICS @ command – Reset Scale
2	0	SICS Z command – Zero Scale
3	0	SICS T command – Tare Scale
4	0	SICS TI command – Tare Scale
5	2 Tare Weight Units	SICS TA command – Tare Scale Write tare weight value to R2.
6	0	SICS TAC command – DeleteTare Weight
7	0	SICS R0 command – Switch Keyboard On
8	0	SICS R1 command – Switch Keyboard Off
9	1=Units Type	SICS U command – Change Units



The following errors are reported upon command completion.

**Table 6 - Command Errors**

<b>Command Number</b>	<b>Error code and Description</b>
1	None
2	1 – Command not Executed 2 – Zero-set range dropped below 3 – Zero-set range exceeded
3	1 – Command not Executed 2 – Tare range dropped below 3 – Tare range exceeded
4	1 – Command not Executed 2 – Tare range dropped below 3 – Tare range exceeded
5	1 – Command not Executed 2 – Tare range dropped below 3 – Tare range exceeded 4 – Tare Data Invalid
6	1 – Command not Executed
7	None
8	None
9	5 – Invalid

**Table 7 - Units Codes**

<b>Unit Number</b>	<b>Description</b>
1	Kg
2	G
3	LB
4	OZT
5	OZ
6	SWT

### **4.3 Steps for User Commands**

1. For commands, which do not require any parameters, simply write the command number into R1. Note: for commands, which require parameters, write the parameter values in R2 and R3 first. Then write the command number.
2. The command execution will begin. All invalid commands are ignored. The driver will format the command and send it to the weigh scale.
3. If the command completes successfully, R1 and R21 will be set to 0. If an error occurs, R1 will be set to 0 and R21 will have an error code as described above.



## **5 Operational Check**

### **5.1 Scope**

The following sections provide some assistance to ensure the interface is working properly.

### **5.2 Verify Hardware and Software Version Number**

The user can verify that the SEG T3770 driver has been installed using the DeltaV Diagnostics tool. The Diagnostics tool will show the Hardware Revision No. (HwRev) and the Software Revision No. (SwRev).

To begin the DeltaV Diagnostic tool select Start-> DeltaV-> Operator-> Diagnostics. In the Diagnostics tool expand the Controller, I/O and then double click on the Programmable Serial Interface Card that has the SEG T3770 driver installed.

The following information will be displayed:

:	:	:
HwRev	Hardware Revision	1.1 (or later)
SwRev	Software Revision	P1.0 (or later)

### **5.3 Verify Configuration**

- Verify port configuration: The serial port must be enabled. User needs to make sure communication settings such as baud rate, parity, and number of data bits match the SEG T3 device settings.
- Verify dataset configuration: The datasets configured must be as shown above.

### **5.4 Verify I/O Communication With Control Studio**

User can create I/O modules in the control studio to verify correct values are read from the SEG T3 Weigh Scale and the PSIC. For input data, the values should be changed in the SEG T3 and verified that the new data are correctly reported.

### **5.5 Using Diagnostics**

- Verify PSIC communication: Select the PSIC on Diagnostics and press the right mouse button. Select Display Real -Time Statistics from the drop down menu. If the Programmable Serial Interface Card is functioning then the user will see the Valid Responses counter and the Async and/or Sync Transactions counters incrementing. There will not be any error counting up.



- Verify port statistics: Select the Port on the Programmable Serial Interface Card and press the right mouse button. Then select Display Port Statistics from the drop down menu. Verify that the port communications statistics are being displayed properly and are counting as expected for the SEG T3 protocol's functionality.
- Verify dataset values: Select a dataset and press the right mouse button. Select View Dataset Registers from the Drop down window. Verify that the dataset values are displayed as expected.

## **5.6 LED Indication**

The Yellow LED for the port should be on solid when all communications on that port are valid. The Yellow LED should be blinking if there is some valid communications and some communications with errors on that port. The Yellow LED should be OFF if there are no valid communications on that port.



## 6 DeltaV - SEG T3 Electrical Interface

The electrical interface between DeltaV and the SEG T3 devices conforms to the RS-232 protocol. The RS-232 cable connecting SEG T3 and the DeltaV PSIC should not exceed 50 feet as specified by the EIA standard for RS-232 protocol.

The SEG T3 uses an 9-pin D-Shell connector, and a prefabricated cable. This cable must be acquired from SEG T3. One end of the SEG T3 Cable fits the 8-pin circular socket. The other end is a 9-pin d-shell plug. To connect the DeltaV Serial Card Termination Block to the ID7, fabricate a cable with a 9-pin d-shell socket on one end and open conductors on the other end. The 9-pin socket should have the following pin out.

Pin Number	Description
1	No connection
2	32
3	33
4	
5	31
6	
7	jumper to pin 8
8	jumper to pin 7
9	No Connection

On the open end of the cable, only 3 conductors are used. These are Rx, Tx and Gnd. Screw down these conductors to the terminal block as indicated below. Lastly, install a jumper between 7 and 8 for port 1, and 15 and 16 for port 2.

Terminal Number	Signal Description
1	Port 1 - Isolated Ground (GND)
2	Unused
3	Port 1 - Transmit Data (TXD)
4	Unused
5	Port 1 - Receive Data (RXD)
6	Unused
7	Port 1 - Data Terminal Ready (DTR)
8	Port 1 - Dataset Ready (DSR)
9	Port 2 - Isolated Ground (GND)
10	Unused
11	Port 2 - Transmit Data (TXD)
12	Unused
13	Port 2 - Receive Data (RXD)
14	Unused
15	Port 2 - Data Terminal Ready (DTR)
16	Port 2 - Dataset Ready (DSR)



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## **Technical Support**

For technical support or to report a defect, please give MYNAH Technologies a call at (636) 681-1555. If a defect is discovered, please document it in as much detail as possible and then fax your report to us at (636) 681-1660.

For Product functionality and Commercial issues, ask for people in the following order:

1. Martin Berutti
2. Jane Wagner

You can also send us your questions via e-mail. Our address is:

[support@mynah.com](mailto:support@mynah.com)

Thank you for using DeltaV.